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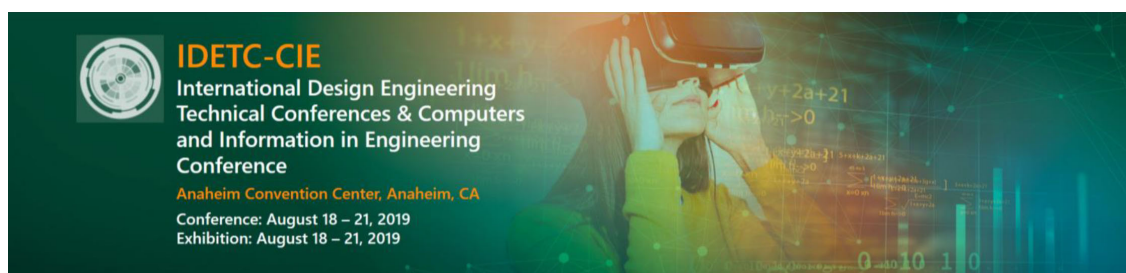
Betreff: **CALL FOR PAPERS 7th Symposium on Origami-Based Engineering Design**

Datum: 25. Januar 2019 um 13:59:33 MEZ

An: <Erster-vorsitz@papierfalten.de>

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The 7th Symposium on Origami-Based Engineering Design
will be held in conjunction with the 43rd ASME Mechanisms & Robotics Conference
August 18-21, 2019, Anaheim, California



CALL FOR PAPERS

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43rd American Society of Mechanical Engineers (ASME) Mechanisms & Robotics
Conference at the ASME 2019 International Design Engineering Technical
Conferences August 18-21, 2019, Anaheim, California

<https://www.asme.org/events/idetccie>

Origami shows great promise for providing insight and inspiration for future discoveries and new applications. The 7th Symposium on Origami-Based Engineering Design builds on previous years' symposia and will provide a venue for researchers to present their work, interact with other researchers in the field, and discuss future trends. The symposium will consist of a keynote talk, technical presentations by authors of accepted papers, and opportunities for informal discussions and networking.

As a leading forum for engineering design topics, the ASME International

Engineering Design Technical Conferences (IDETC) is an ideal venue for bringing together researchers from various backgrounds. Submissions are invited from all disciplines interested in origami-based engineering design. Topics include but are not limited to origami modelling, origami design methods, enabling materials, tessellations, and origami-inspired applications. Papers on related topics are encouraged.

Submission Instructions

Authors will submit an abstract together with a full-length paper that will be peer reviewed. Abstracts and papers are submitted to the ASME IDETC website at;

<https://www.asme.org/events/idetccie>

From the conference homepage, login using your author account. Select the “43rd Mechanisms and Robotics Conference (MR),” choose “Technical Paper Publication,” and “Origami-Based Engineering Design,” and then follow the instructions for submission.

Related Special Issue of the ASME Journal of Mechanisms and Robotics

A special issue of selected papers from the Mechanisms and Robotics Conference, including the Symposium on Origami Based Engineering Design, will be considered for publication in the ASME Journal of Mechanisms and Robotics. ASME policies allow authors to submit a journal-quality version of the conference paper to the journal without further copyright permissions, and authors enter the corresponding conference paper number during submission to the journal. The conference and journal will have separate submission and review processes.

Publication Schedule

The paper submission deadlines are governed by the IDETC organisers.

The following deadlines are set:

Submission of Abstract and Full-Length Paper for Review.....February 25, 2019

Notification of Acceptance/Revision Decision.....April 8, 2019

Conference papers will be made available on-line and in the on-line conference proceedings.

Symposium Organizers

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